

## ABSTRACT OF THE DISCLOSURE

A control method of an open type motion simulation system, the method includes the steps of: a simulation system linked to a motion system; the simulation system outputting open type command to the motion system; the motion system simultaneously performing operation and analysis on the open type command and platform feedback data by platform dynamic algorithm principle of a control ware; and the motion system then outputting control signal to a control driver to drive the platform.

097855255.025004